

# Geometric Control and Homotopic Methods for solving a Bang-Singular problem

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Figure: (LHS) Hard pulse of  $90^\circ$ . (RHS) Optimal solution.

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# Contrast problem

$$\begin{cases}
 |q_2(t_f)|^2 = (y_2^2(t_f) + z_2^2(t_f)) \rightarrow \max & q_i = (y_i, z_i), |q_i| \leq 1, i = 1, 2 \\
 \left[ \begin{array}{l} \dot{y}_1 = -\Gamma_1 y_1 - u z_1 \\ \dot{z}_1 = \gamma_1(1 - z_1) + u y_1 \\ \dot{y}_2 = -\Gamma_2 y_2 - u z_2 \\ \dot{z}_2 = \gamma_2(1 - z_2) + u y_2 \end{array} \right. & \begin{array}{l} \gamma_i = 1/(32.3T_{i1} \cdot 10^{-3}) \\ \Gamma_i = 1/(32.3T_{i2} \cdot 10^{-3}) \end{array} \\
 q_1(0) = (0, 1) = q_2(0) & |u| \leq 2\pi \\
 q_1(t_f) = (0, 0) &
 \end{cases}$$

Spin 1 ( $y_1, z_1$ ) - Deoxygenated blood :  $T_{11} = 1350$  ms,  $T_{12} = 50$  ms  
 Spin 2 ( $y_2, z_2$ ) - Oxygenated blood :  $T_{21} = 1350$  ms,  $T_{22} = 200$  ms

Spin 1 ( $y_1, z_1$ ) - Cerebrospinal fluid :  $T_{11} = 2000$  ms,  $T_{12} = 200$  ms  
 Spin 2 ( $y_2, z_2$ ) - Water :  $T_{21} = 2500$  ms,  $T_{22} = 2500$  ms

Blood:  $T_{min} = 6.7980978$

Fluid:  $T_{min} = 20.2301921$

# Pontryagin Maximum Principle

- We have a (smooth) Mayer problem of the form:

$$\min_{u \in \mathcal{U}} c(q(t_f)), \quad \dot{q} = F(q) + uG(q), \quad q = (q_1, q_2) \in \mathbb{R}^4, \quad |u| \leq 2\pi, \quad u \in \mathbb{R},$$

where

- $c(q(t_f)) = -(y_2^2(t_f) + z_2^2(t_f))$
  - $F(q) = \sum_{i=1,2} (-\Gamma_i y_i) \frac{\partial}{\partial y_i} + (\gamma_i (1 - z_i)) \frac{\partial}{\partial z_i}$
  - $G(q) = \sum_{i=1,2} -z_i \frac{\partial}{\partial y_i} + y_i \frac{\partial}{\partial z_i}$
- The Hamiltonian is:  $H(q, p, u) = \langle p, F(q) + uG(q) \rangle$
  - And the Maximum Principle gives:  $\begin{cases} u = 2\pi \operatorname{sign}(H_G) \text{ is bang} & \text{if } H_G \neq 0 \\ u \text{ is singular} & \text{if } H_G = 0 \end{cases}$
  - The boundary conditions are:

$$q_1(t_f) = 0 \quad (\text{zero magnetization of the first spin})$$

$$p_2(t_f) = -2p^0 q_2(t_f), \quad p^0 \leq 0.$$

# Simplest possible solution

- The north pole  $N = ((0, 1), (0, 1)) = x(0)$ , is an equilibrium point for the singular control system ( $u_s = 0$ ): **start with a bang**.
- Due to symmetry of revolution: the first bang is either  $u = +2\pi$  or  $u = -2\pi$ .
- A bang solution amounts roughly to a **rotation** of each plane  $(y_i, z_i)$  around 0.
- At  $t_f$ ,  $q_1(t_f) = 0$ , and there is no improvement by rotation (because  $T_{21} > T_{22}$ ) of the contrast: **no bang at the end**.

## Lemma

*The simplest BC-extremal in the contrast problem is of the form  $B^+S$ .*

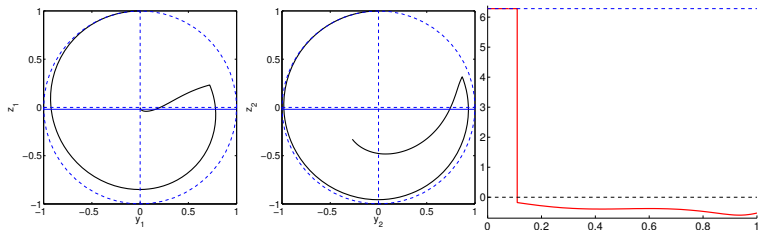


Figure: Trajectories of spin 1, 2 and the control associated for the Blood case.

# Singular extremals

The Hamiltonian is  $H(q, p, u) = H_F(q, p) + u H_G(q, p)$ ,  $H_F := \langle p, F \rangle$ ,  $H_G := \langle p, G \rangle$ .

Let  $z(\cdot) = (q(\cdot), p(\cdot))$  be a **singular extremal**, then  $H_G(z(\cdot)) = 0$  identically.

Differentiating with respect to time,

$$\left. \begin{aligned} \frac{dH_G}{dt}(z(t)) &= \{H, H_F\}(z(t)) = \{H_G, H_F\}(z(t)) = 0 \\ H_G(z(t)) &= 0 \end{aligned} \right\} \text{(2 constraints)}$$

$$\frac{d^2 H_G}{dt^2}(z(t)) = \{\{H_G, H_F\}, H_F\}(z(t)) + u_s(t) \{\{H_G, H_F\}, H_G\}(z(t)) = 0$$

Besides,

- + we can restrict  $p$  to  $H_s = h$  because of the homogeneity :  $u_s(q, \alpha p) = u_s(q, p)$ .
- + generalized Legendre-Clebsch condition has to be satisfied that is  $\{\{H_G, H_F\}, H_G\} \geq 0$ .

$\Rightarrow$  for each  $q(0) \in \mathbb{R}^4$ ,  $p(0) \in \mathbb{R}^4$  lives in half a straight line and the **singular flow** starting from  $q(0)$  is a **surface of dimension 2**.

# Singular extremals in the Fluid case

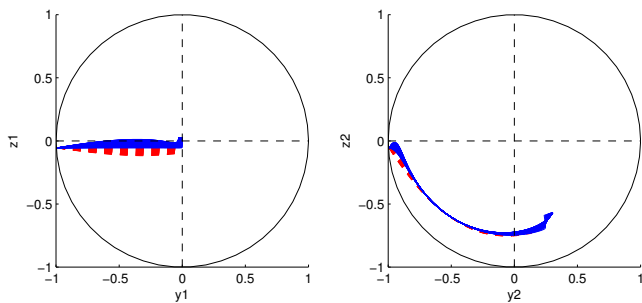


Figure: Singular surface with blowing up control in red ( $\{\{H_G, H_F\}, H_G\}$  tends to 0).

# Singular extremals in the Fluid case

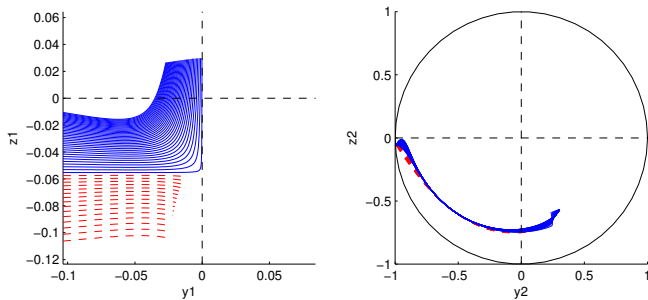


Figure: Zoom of singular surface with blowing up control in red ( $\{\{H_G, H_F\}, H_G\}$  tends to 0).



## Définition

Let  $z(\cdot)$  be a reference singular solution of  $\vec{H}_s$  on  $[0, t_f]$ . The variational equation on the tangent space to  $\Sigma_s := \{H_G = \{H_F, H_G\} = 0\}$

$$\begin{aligned}\dot{\delta z} &= d\vec{H}_s(z(t))\delta z \\ dH_G &= d\{H_F, H_G\} = 0\end{aligned}$$

is called Jacobi equation.

- A Jacobi field  $J(t) = (\delta q, \delta p)$  is a non-zero solution of Jacobi equation.
- It is said semi-vertical at time  $t$  if  $\delta q(t) \in \mathbb{R}G(q(t))$ .
- A time  $t \in (0, t_f]$  is said to be conjugate if there exists a Jacobi field  $J(t)$  semi-vertical at 0 and  $t$ .

## Theorem

Under strict Legendre-Clebsch condition (i.e.  $\{\{H_G, H_F\}, H_G\} > 0$ ) and additional generic assumptions, the **absence of conjugate times** on  $(0, t_f)$  is **necessary** for local optimality of a singular arc.

# Conjugate points for singular extremals in the Fluid case

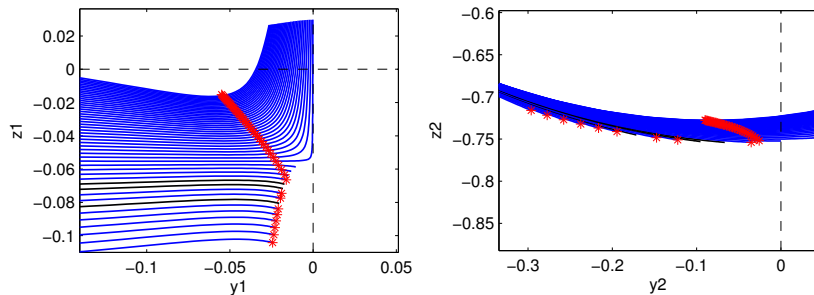


Figure: Zoom of singular surface with conjugate points in red.

⇒ We can expect more intricate structures than  $BS$  in the fluid case.

# The limit case $t_f = T_{min}$ . Single spin problem (see [BCG<sup>+</sup>11])

$$(P_1) \left\{ \begin{array}{l} t_f \rightarrow \min \\ \begin{cases} \dot{y} = -\Gamma y - uz \\ \dot{z} = \gamma(1-z) + uy \end{cases} \\ q(0) = (0, 1) \\ q(t_f) = (0, 0) \end{array} \right. \quad \begin{array}{l} q = (y, z), |q| \leq 1 \\ \frac{3\gamma}{2} < \Gamma \\ |u| \leq 2\pi \end{array}$$

The dynamics:  $\dot{q} = F(q) + u G(q)$

The Hamiltonian:  $H(q, u, p) = H_F(q, p) + u H_G(q, p)$ ,  $H_i = \langle p, F_i \rangle$ ,  $i = F, G$

$\Rightarrow$  The **singular extremals** are those contained in  $H_G = 0$ .

[BCG<sup>+</sup>11] B. Bonnard, O. Cots, S. Glaser, M. Lapert, and D. Sugny.  
Geometric optimal control of the contrast imaging problem in nuclear magnetic resonance.  
*math.u-bourgogne.fr*, 2011.

# Single spin: singular extremals

⇒ The **singular extremals** are those contained in  $H_G = 0$ .

$$\left. \begin{aligned} H_G &= \langle p, G \rangle = 0 \\ \dot{H}_G &= \langle p, [G, F] \rangle = 0 \end{aligned} \right\} \Rightarrow \det(G, [G, F]) = y(-2\delta z + \gamma) = 0$$

with  $\delta = \gamma - \Gamma$ .

The singular lines are  $y = 0$  and  $z_0 = \frac{\gamma}{2\delta}$ . The singular control  $u_s(q, p)$  is computed from  $\ddot{H}_G = \{\{H_G, H_F\}, H_F\}(z) + u_s \{\{H_G, H_F\}, H_G\}(z) = 0$ .

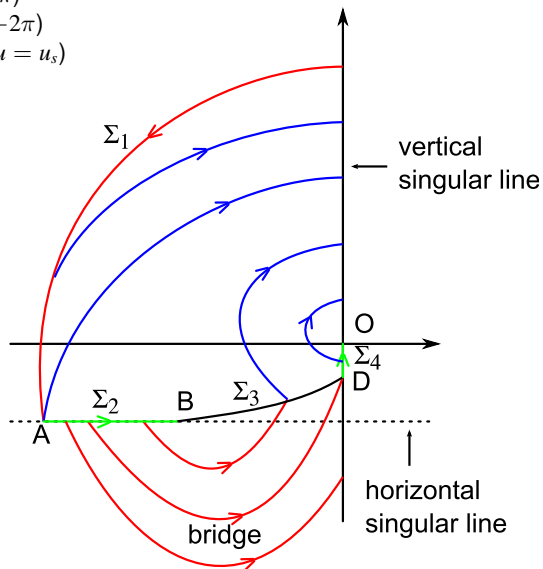
**Horizontal line** ( $z_0 = \frac{\gamma}{2\delta}$ ): optimal, according to Generalized Legendre-Clebsch condition (see [BC03]) and  $u_s(q) = \gamma(2\Gamma - \gamma)/(2\delta y) \Rightarrow u_s \in L^1, u_s \notin L^2$

**Vertical line** ( $y = 0$ ): optimal for  $z_0 < z < 1$  (GLC) and  $u_s(q) = 0$ .

[BC03] B. Bonnard and M. Chyba.  
Singular trajectories and their role in control theory, mathématiques & applications, vol. 40.  
lavoisier.fr, Jan 2003.

# Single spin: global synthesis

- Red: bang ( $u = 2\pi$ )
- Blue: bang ( $u = -2\pi$ )
- Green: singular ( $u = u_s$ )
- B: saturation



## Summary: single spin => contrast problem

- Solutions of the contrast problem are made of **Bang-Singular sequences**.
- We get  $T_{min}$ .
- The solution for the limit case  $t_f = T_{min}$  is  $B^+SB^+S$ .

To solve the contrast problem, we use an **indirect method** (multiple shooting)

⇒ we need to know the **structure a priori**.

⇒ we use an **homotopic approach** to capture the structure and initialize the multiple shooting method.

$$(P_\lambda) \left\{ \begin{array}{l}
 - (y_2^2(t_f) + z_2^2(t_f)) + (1 - \lambda) \int_0^{t_f} |u|^{2-\lambda}(t) dt \rightarrow \min \\
 q_i = (y_i, z_i), |q_i| \leq 1, i = 1, 2 \\
 \left[ \begin{array}{lll}
 \dot{y}_1 = - \Gamma_1 y_1 & - & u z_1 \\
 \dot{z}_1 = & \Gamma_1 (1 - z_1) & + & u y_1 \\
 \dot{y}_2 = - \Gamma_2 y_2 & - & u z_2 \\
 \dot{z}_2 = & \Gamma_2 (1 - z_2) & + & u y_2
 \end{array} \right. \quad \begin{array}{l}
 \Gamma_i = 1/(32.3 T_{i1}) \\
 \Gamma_i = 1/(32.3 T_{i2})
 \end{array} \\
 q_1(0) = (0, 1) = q_2(0) \\
 q_1(t_f) = (0, 0)
 \end{array} \right. \quad |u| \leq 2\pi$$

Homotopy  $(P_\lambda)$ :  $- (y_2^2(t_f) + z_2^2(t_f)) + (1 - \lambda) \int_0^{t_f} |u|^{2-\lambda}(t) dt \rightarrow \min$

The Hamiltonian:  $H(q, u, p, \lambda) = H_F(q, p) + u H_G(q, p) + (1 - \lambda) |u|^{2-\lambda}$

$(P_\lambda)$ -extremals are **admissible** for  $(P)$ .

# Maximum principle

The maximization of the Hamiltonian gives:

$$u(q, p, \lambda) = \underset{w \in U}{\operatorname{argmax}} H(q, w, p, \lambda)$$

and we have

$$\lambda < 1 \Rightarrow u = \operatorname{sign}(H_G) \min \left( 2\pi, \left( \frac{2|H_G|}{((2-\lambda)(1-\lambda))} \right)^{\frac{1}{(1-\lambda)}} \right)$$

We call **true Hamiltonian** the function (which does not depend on  $u$ )

$$H_r(q, p, \lambda) = H(q, u(q, p, \lambda), p, \lambda)$$

In order to solve the problem  $(P)$  in  $\lambda = 1$ , we:

- 1 solve by **simple shooting method** the problem in  $\lambda = 0$  easily,
- 2 use **homotopic method** to solve  $(P_\lambda)$ , from  $\lambda = 0$  to  $\lambda = \lambda_f < 1$ , to ...
- 3 ... **capture the structure** of  $(P)$  and **initialize** the **multiple shooting method**.



Smooth optimal control problem  $(P_\lambda)$

(PMP)

$$(BVP_\lambda) \begin{cases} (\dot{x}, \dot{p}) = \vec{H}(x, p, \lambda) = \left( \frac{\partial H(x, p, \lambda)}{\partial p}, -\frac{\partial H(x, p, \lambda)}{\partial x} \right) \\ b_0(x(0), p(0), \lambda) = 0 \in \mathbb{R}^n \\ b_f(x(t_f), p(t_f), \lambda) = 0 \in \mathbb{R}^n \end{cases}$$

(Shooting method)

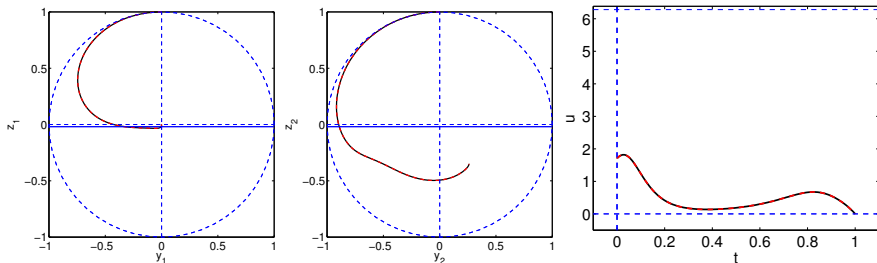
$$S_\lambda(x_0, p_0) = \begin{pmatrix} b_0(x_0, p_0, \lambda) \\ b_f(x_f, p_f, \lambda) \end{pmatrix} = 0 \quad (S : \mathbb{R}^{2n} \rightarrow \mathbb{R}^{2n})$$

with  $(x_f, p_f) \equiv (x(t_f, x_0, p_0, \lambda), p(t_f, x_0, p_0, \lambda)) = \exp_{t_f} \vec{H}(x_0, p_0, \lambda)$

# 1: Solving in $\lambda = 0$ with simple shooting method: Blood case

The final time  $t_f$  is equal to  $1.1T_{min}$  where  $T_{min}$  is the minimal time to transfer the spin 1 from  $(0, 1)$  to  $(0, 0)$ .

Blood case: Spin 1 = (De)oxygenate blood :  $T_{11} = 1350$  and  $T_{21} = 200$   
Spin 2 = Oxygenate blood :  $T_{12} = 1350$  and  $T_{22} = 50$



**Figure:** Solution for  $\lambda = 0$  with  $L^{2-\lambda}$  regularization. Trajectories of spin 1 and 2 and the control associated.

## 2: homotopic method

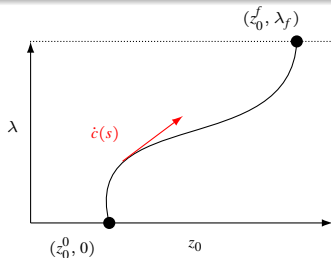
Let us define the homotopic function

$$\begin{aligned} h : \mathbb{R}^{2n} \times [0, 1] &\longrightarrow \mathbb{R}^{2n} \\ (z_0, \lambda) &\longmapsto S_\lambda(z_0) \end{aligned}$$

with  $z_0 = (q_0, p_0)$ .

Assuming that 0 is a regular value for  $h$ , the level set  $\{h = 0\}$  is a one dimensional submanifold of  $\mathbb{R}^{2n+1}$  called the **path of zeros**.

We know a zero of  $h(\cdot, \lambda)$  for  $\lambda_0 = 0$  noted  $z_0^0$ , and we want to follow this path to reach a zero for a target value of the parameter  $\lambda$  close to 1.



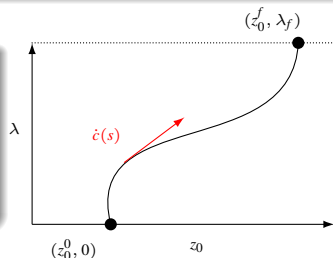
HAMPATH uses DOPRI5 from E. Hairer and G. Wanner [HrW93] [HW], for the numerical integration (without any correction) of:

$$(IVP) \begin{cases} \dot{c}(s) = T(c(s)) \\ c(0) = (z_0^0, 0) \end{cases}$$

Until  $s_f$  such that  $\lambda(s_f)$  close to 1 (dense output).

$\dot{c}(s) = T(c(s))$  is determined by

- 1  $h'(c(s))\dot{c}(s) = 0$
- 2  $|\dot{c}(s)| = 1$
- 3  $\det \begin{pmatrix} h'(c(s)) \\ \dot{c}(s) \end{pmatrix}$  is of constant sign



[HrW93] E. Hairer, S.P. Nørsett, and G. Wanner. *Solving Ordinary Differential Equations I, Nonstiff Problems*, volume 8 of *Springer Serie in Computational Mathematics*. Springer-Verlag, second edition, 1993.

[HW] E. Hairer and G. Wanner. DOPRI5 <http://www.unige.ch/~hairer/prog/nonstiff/dopri5.f>.

# The path of zeros: $\lambda_f = 0.915$ : Blood case

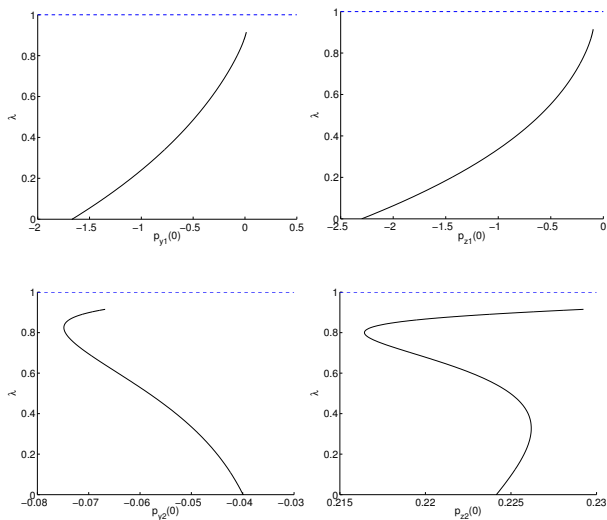
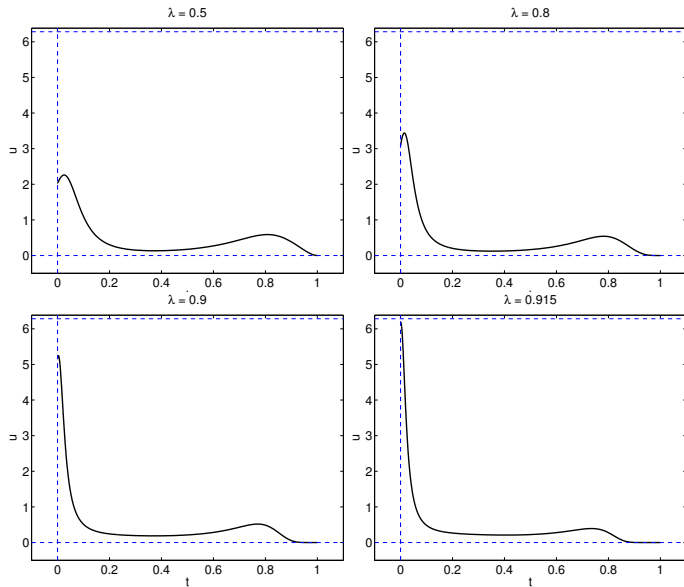
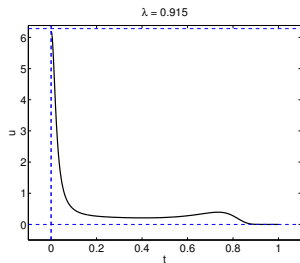


Figure: Homotopic path with  $L^{2-\lambda}$  regularization. Initial adjoint vector w.r.t.  $\lambda$ .

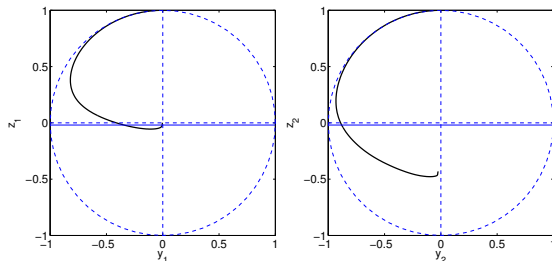
# Control: $\lambda \in \{0.5, 0.8, 0.9, 0.915\}$ : Blood case



# States-Control: $\lambda = 0.915$ : Blood case



→ Bang-Singular structure.



**Figure:** Solution for  $\lambda = 0.915$  with  $L^{2-\lambda}$  regularization. Trajectories of spin 1 and 2 and the control associated.

### 3: multiple shooting

We have a **BS** structure for  $t_f = 1.1T_{min}$ . We denote by  $t_0, t_1, t_f$  the different instants and by  $z_0, z_1, z_f$  the the associated state and costate variables ( $z = (q_1, q_2, p_1, p_2) \in \mathbb{R}^4 \times \mathbb{R}^4$ ).

- **Hamiltonian :**

$$H(q, u, p) = H_F(q, p) + u H_G(q, p), \begin{cases} u = 2\pi & \text{if } t \in [t_0; t_1] \\ u = u_{sing} & \text{if } t \in [t_1; t_f] \end{cases}$$

- **Equations (cf. [Mau76]) :**

	<i>Bang</i>		<i>Sing</i>	
$(t_0, z_0)$	$\longrightarrow$	$(t_1, z_1)$	$\longrightarrow$	$(t_f, z_f)$
$q_1 = (0, 1)$		$H_G = 0$		$q_1 = (0, 0)$
$q_2 = (0, 1)$		$\dot{H}_G = 0$		$q_2 = p_2$

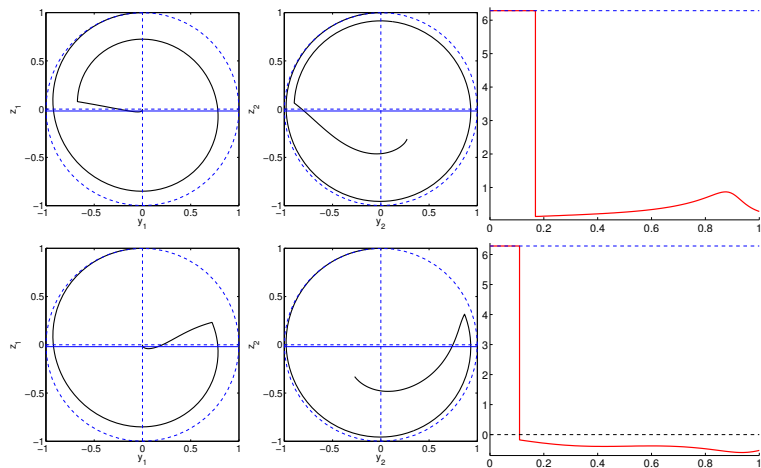
with the matching conditions  $z(t_1; t_0, z_0) = z_1$ .

[Mau76] H. Maurer.  
Numerical solution of singular control problems using multiple shooting techniques.  
*Journal of optimization theory and applications*, Jan 1976.



# Trajectories of spin 1 and 2 and the control: blood case ( $\lambda = 1.0$ )

We used the solution at  $\lambda = 0.915$  to initialise the multiple shooting. The time  $t_1$  is taken in  $[0.01, 0.2]$  and leads to the following solutions.



**Figure:** (TOP) First solution (contrast of 0.41). (BOTTOM) Second solution (contrast of 0.42). From the  $L^{2-\lambda}$  regularization.

# Trajectories of spin 1 and 2 and the control: blood case ( $\lambda = 1.0$ )

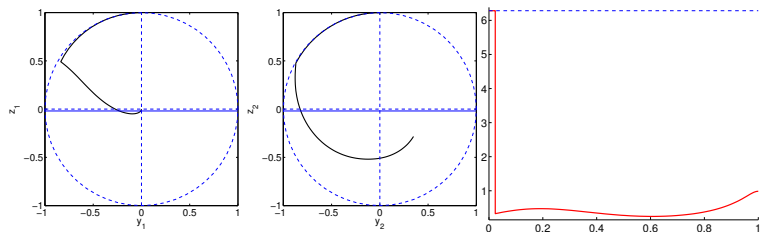


Figure: Best solution (contrast of 0.45) from the  $L^{2-\lambda}$  regularization.

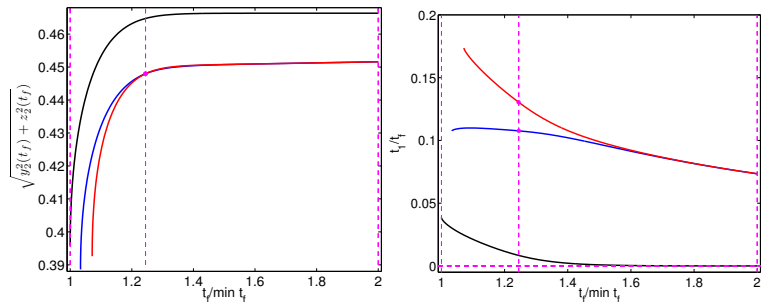
- The regularizations  $L^{2-\lambda}$  **permit to find solutions** satisfying the first order necessary conditions of optimality and *BS* structure has been detected.
- To solve in  $\lambda = 0$  is very **easy**.
- Homotopy is **automatic**: we do not need to provide any steps grid.
- But there are **many local solutions**.

## Contrast problem: sensitivity w.r.t. the final time $t_f$

We use HAMPATH to perform a differential continuation on  $t_f$  between  $T_{min} + \varepsilon$  and  $2T_{min}$ .

- $T_{min}$  : the minimal time to transfer the spin 1 from  $(0, 1)$  to  $(0, 0)$ .

↪ there is an horizontal asymptote on the contrast plot. 99% of the optimal solution is obtained for  $t_f = 1.3T_{min}$ .



**Figure:** Best solution in black. (LHS) Contrast w.r.t the transfer duration. (RHS) Normalized switching time.

# Solution for the limit case: $t_f$ close to $T_{min}$

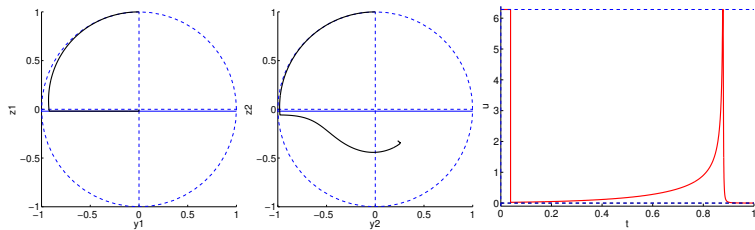


Figure: Best solution for  $t_f = 1.000004 \times \min t_f$ .

# 1: Solving in $\lambda = 0$ for the second example: the fluid case

The final time  $t_f$  is equal to  $1.5T_{min}$  where  $T_{min}$  is the minimal time to transfer the spin 1 from  $(0, 1)$  to  $(0, 0)$ .

Fluid case: Spin 1 = Cerebrospinal fluid :  $T_{11} = 2000$  and  $T_{21} = 200$   
Spin 2 = Water :  $T_{12} = 2500$  and  $T_{22} = 2500$

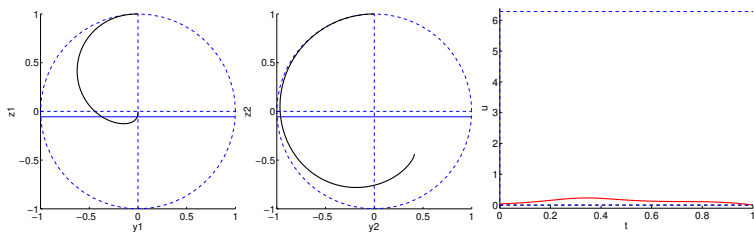


Figure: Solution for  $\lambda = 0$  with  $L^{2-\lambda}$  regularization. Trajectories of spin 1 and 2 and the control associated.

## 2: Homotopy results (on $\lambda$ ): fluid case ( $\lambda_f = 0.954$ )

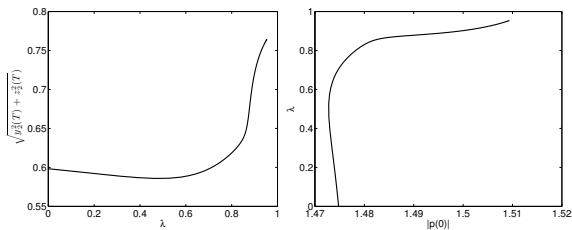


Figure:  $\lambda = 0.0 \rightarrow \lambda = 0.954$ , contrast  $\in [0.586, 0.765]$  and norm of the path.

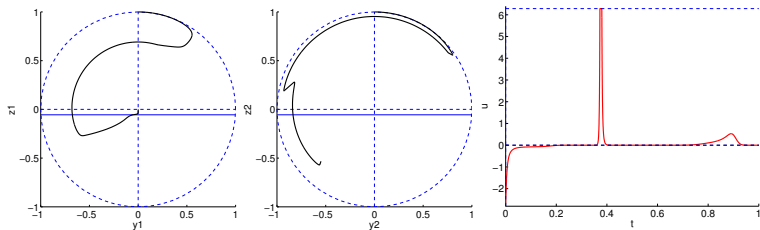


Figure: Solution for  $\lambda = 0.954$  (contrast of 0.765) from the  $L^{2-\lambda}$  regularization.

### 3: Final solution for $\lambda = 1$ and homotopy results (on $t_f$ )

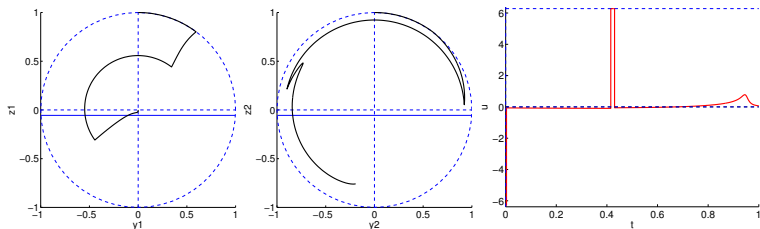


Figure: Solution for  $\lambda = 1$ ,  $t_f = 1.5T_{min}$  (contrast of 0.783) from the  $L^{2-\lambda}$  regularization.

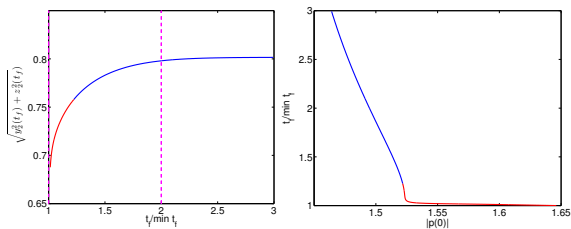


Figure: (BLUE) 2-BS structure. (RED) 3-BS structure. Homotopy:  $t_f = 3T_{min} \rightarrow t_f = T_{min}$ , contrast  $\in [0.69, 0.8]$  and norm of the path.



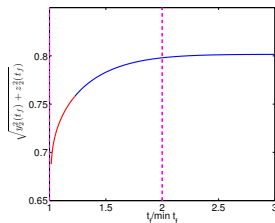


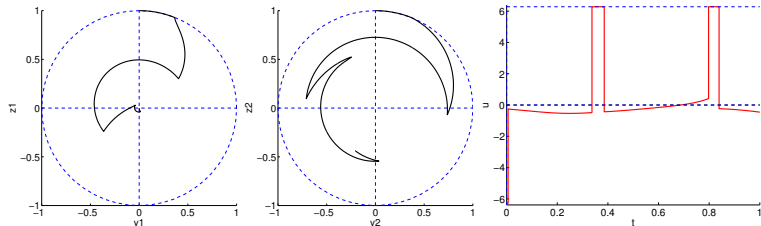
Figure: (BLUE) 2-BS structure. (RED) 3-BS structure. Contrast w.r.t.  $t_f$ .

During the continuation we detect that for  $t_f = 1.225T_{min}$ , the last singular control does not respect the constraint ( $u_s \leq 2\pi$ ). Hence, we add a Bang arc, which consists in adding two switching times in the multiple shooting formulation and we have a 3BS-structure.

## New results in the blood case: homotopy on parameters

Spin 1 ( $y_1, z_1$ ) -	Deoxygenated blood :	$T_{11} = 1350$ ms,	$T_{12} = 50$ ms
Spin 2 ( $y_2, z_2$ ) -	Oxygenated blood :	$T_{21} = 1350$ ms,	$T_{22} = 200$ ms
Spin 1 ( $y_1, z_1$ ) -	Cerebrospinal fluid :	$T_{11} = 2000$ ms,	$T_{12} = 200$ ms
Spin 2 ( $y_2, z_2$ ) -	Water :	$T_{21} = 2500$ ms,	$T_{22} = 2500$ ms

We perform here a continuation on the physical parameters from the Fluid case to the Blood one.



**Figure:** 3BS solution for the blood case, obtained from the 2BS fluid solution. Here  $\lambda = 1.0$ ,  $t_f = 1.5T_{min}$ , contrast is 0.484.

# New results in the blood case: homotopy on the final time

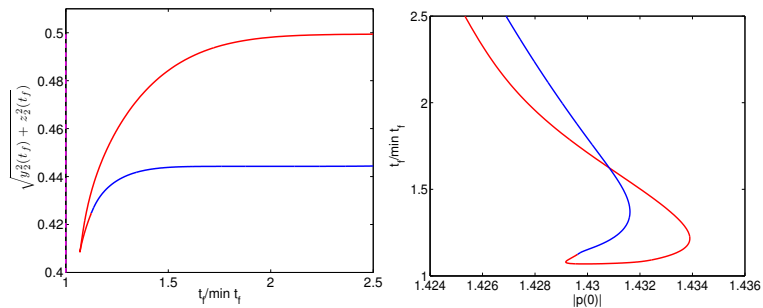
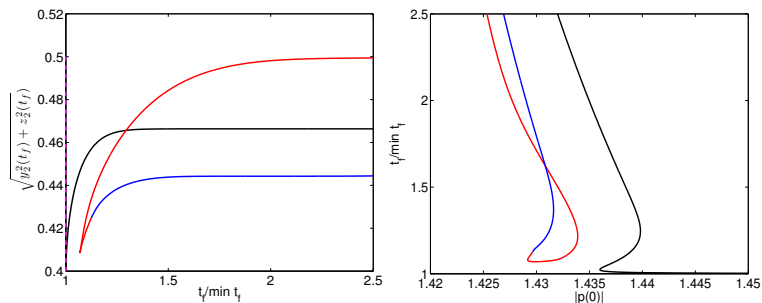


Figure: (BLUE) 2BS-structure. (RED) 3BS-structure. Contrast and norm of the path w.r.t.  $t_f$

# Old and New results in the blood case



**Figure:** (BLACK) *BS*-structure. (BLUE) *2BS*-structure. (RED) *3BS*-structure. Contrast and norm of the path w.r.t.  $t_f$

⇒ The optimal structure varies according to  $t_f$  which is not detected in this case, during the path following.

# Algorithmic aspects: HAMPATH package

From the **true hamiltonian** and the boundary, intermediate and transversality conditions, HAMPATH [CCG11]:

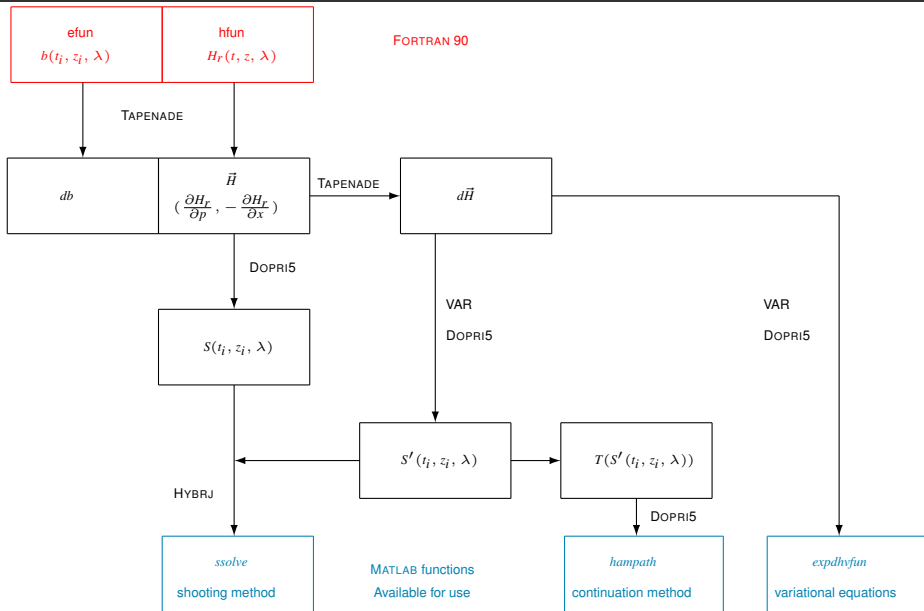
- produces **automatically** the state-costate equations (thanks to **TAPENADE**)
- computes the shooting function by numerical integration (thanks to **DOPRI5**)
- provides the **variational equations** used in the jacobian of the shooting function (thanks to **TAPENADE**)
- integrates the variational equations so that the **diagram commutes** (the step size control is only made on the state and co-state equations)

$$\begin{array}{ccc} (IVP) & \xrightarrow{\text{Numerical integration}} & h(z_0, \lambda) \\ \text{Derivative} \downarrow & & \downarrow \text{Derivative} \\ (VAR) & \xrightarrow{\text{Numerical integration}} & \frac{\partial h}{\partial z_0}(z_0, \lambda) \end{array}$$

[CCG11] J.B. Caillaud, O. Cots, and J. Gergaud.

Differential pathfollowing for regular optimal control problems. HAMPATH [apo.enseeiht.fr/hampath](http://apo.enseeiht.fr/hampath).  
*Optimization Methods and Software*, to appear, 2011.

# Global diagram of HAMPATH



# Conclusion

- The HAMPATH package [CCG11] gives tools to solve OCP by **indirect methods**:
    - Shooting methods: simple and multiple;
    - Homotopic methods: differential without correction;
    - Function which integrate the variational equations and permit to check sufficient second order conditions in the smooth case;
    - ...
  - The derivatives and the functions are computed **accurately** and **automatically**.
  - It is very **easy to use** since only 2 FORTRAN subroutines need to be implemented. Then it is interfaced with MATLAB.
- 
- Homotopic method detects  $BS$  and  $2BS$ -structures and gives **good initial points** for multiple shooting.
  - It gives also some sensitivity w.r.t to the final time and parameters.
  - Finding the global optimum is still an **open problem**.
  - Some work have been done about **second order conditions** for the contrast problem with  $BS$  structure (see [BC12] for details);

[BC12] B. Bonnard and O. Cots.  
Geometric numerical methods and results in the control imaging problem in nuclear magnetic resonance.  
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